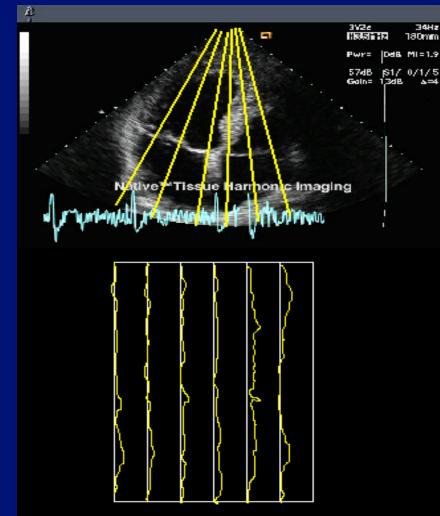
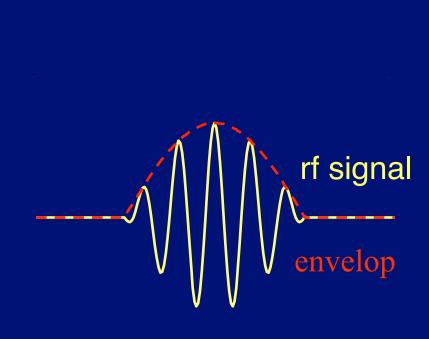
<u>Chapter 5:</u> Diffraction and Beam Formation Using Arrays

# **B-mode Imaging**

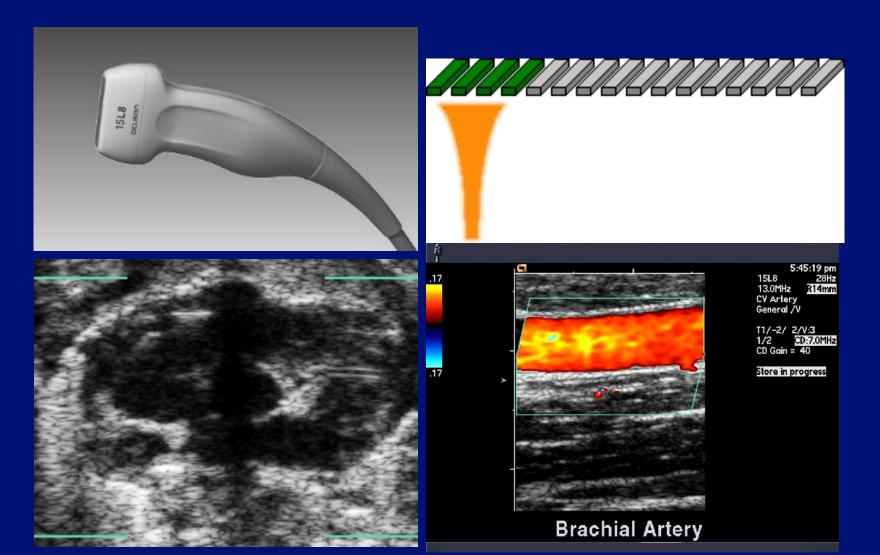
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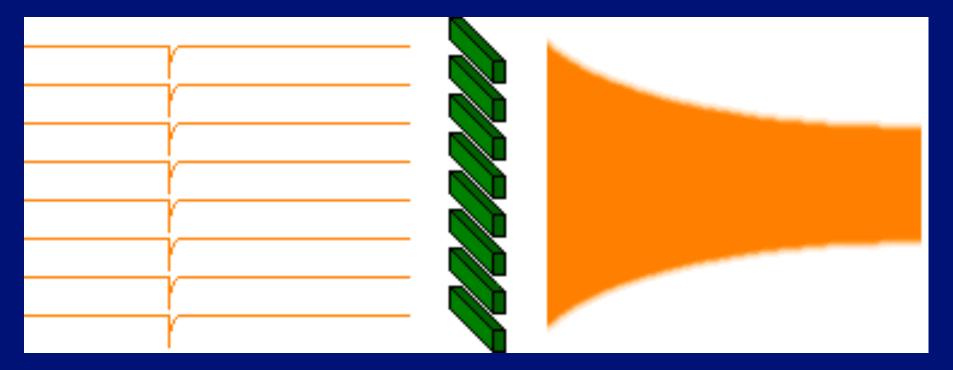
$$p(t - \frac{2z'}{c}) = A(t - \frac{2z'}{c})\cos(2\pi f_0(t - \frac{2z'}{c}))$$

# Linear Scanning



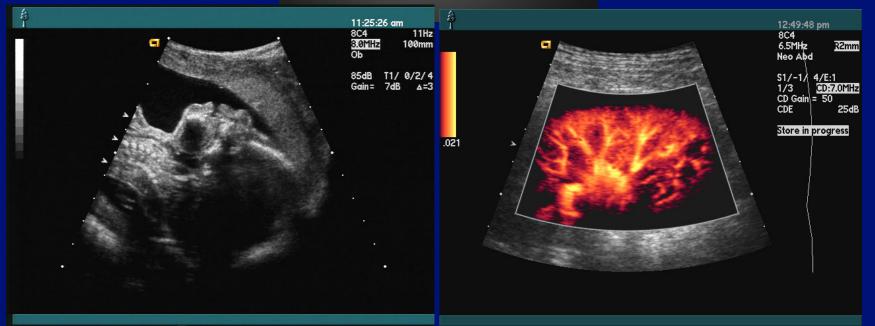
# **Beam Formation Using Arrays**

### Focusing:

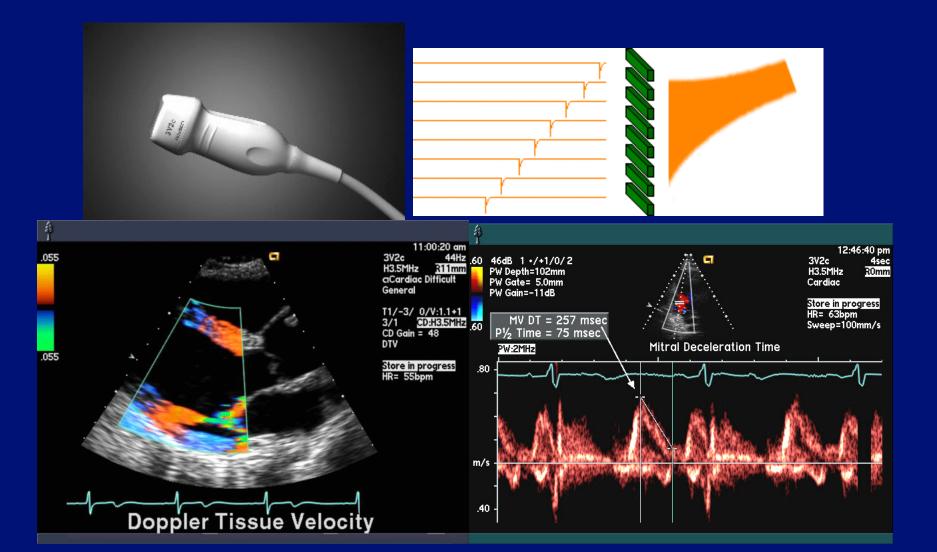


# **Curved Linear Scanning**

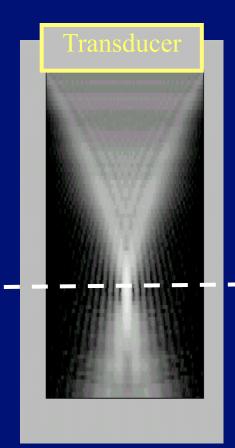




## Sector Steering



# Focusing $\leftarrow \rightarrow$ Beam Formation

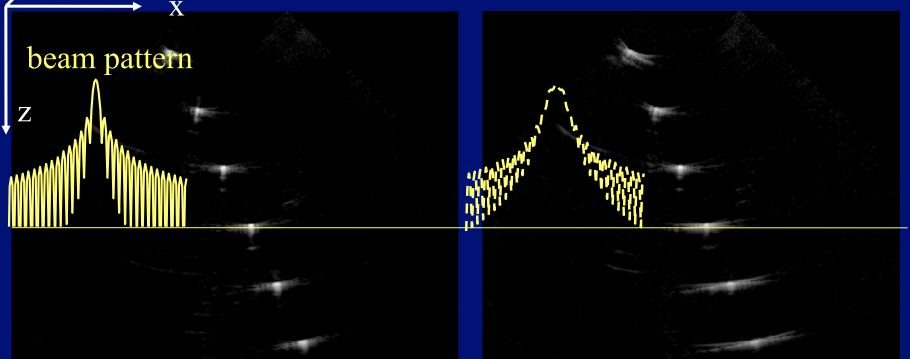


To form a beam of sound wave such that only the objects along the beam direction are illuminated and possibly detected. Mainlobe Sidelobe

### Nomenclature

### Good Focusing

#### **Poor Focusing**



x: Lateral, azimuthal, scany: Elevational, non-scanz: Axial, range, depth

Beam pattern Radiation pattern Diffraction pattern Focusing pattern



# Beamforming

- Manipulation of transmit and receive apertures.
- Trade-off between performance/cost to achieve:
  - Steer and focus the transmit beam.
  - Dynamically steer and focus the receive beam.
  - Provide accurate delay and apodization.
  - Provide dynamic receive control.

# Imaging Model



A-scan:

$$V(t) = k \iiint \frac{R(x', y', z') e^{-2\beta z'}}{z'} B(x', y', z') p(t - \frac{2z'}{c}) dx' dy' dz'$$

**B-scan**:

$$S(x,t) = k \iiint R(x',y',z') B(x'-x,y',z') p(t-\frac{2z'}{c}) dx' dy' dz'$$

Scanning  $\rightarrow$  Convolution (Correlation vs. Convolution)

# Imaging Model

$$p(t - \frac{2z'}{c}) = A(t - \frac{2z'}{c})\cos(2\pi f_0(t - \frac{2z'}{c}))$$

Ideally,

 $S(x,t) = R(x,y_0,ct/2)$ 

In practice,

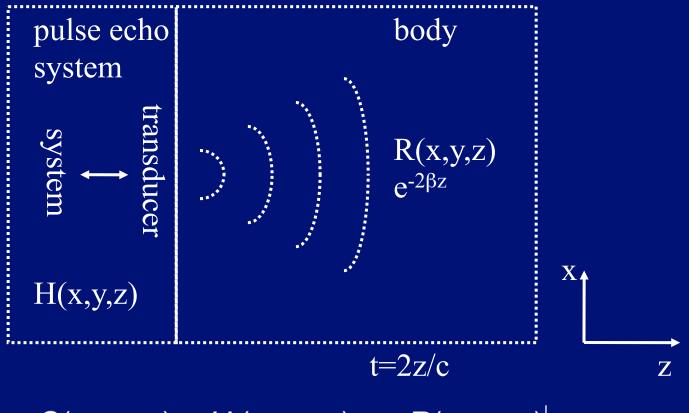
 $B(\mathfrak{a})$ : determined by diffraction  $A(\mathfrak{a})$ : determined by transducer bandwidth

# **Beam Formation as Spatial Filtering**

• Propagation can be viewed as a process of linear filtering (convolution).

•Beam formation can be viewed as an inverse filter (or others, such as a matched filter).

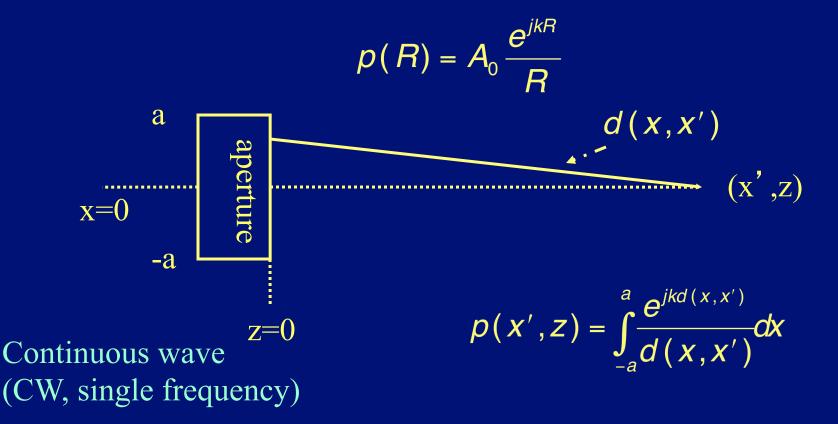
# Imaging Model



 $S(x, y, z) = H(x, y, z) * * R(x, y, z)|_{z=ct/2}$ 

### **Diffraction from 1D Apertures**

• Free space Green's function:



# In the Fresnel Region

$$Z^{2} \gg (X - X')^{2}$$

$$d(x, x') = Z(1 + \frac{(x - x')^{2}}{z^{2}})^{1/2} \approx Z + \frac{(x - x')^{2}}{2z}$$

$$(x', Z) \approx \frac{1}{z} \int_{-a}^{a} e^{jkz} e^{jk(x - x')^{2}/2z} dx = \frac{e^{jkz} e^{jkx'^{2}/2z}}{z} \int_{-a}^{a} e^{-jkxx'/z} e^{jkx^{2}/2z} dx$$

$$C(x) = |C(x)| e^{j\theta(x)}$$

$$p(x', Z) \approx \frac{e^{jkz} e^{jkx'^{2}/2z}}{z} \int_{-a}^{a} C(x) e^{-jkxx'/z} e^{jkx^{2}/2z} dx$$

р

# Focusing in the Far Field (or Focal Point)

*ka*<sup>2</sup> / 2*z* << 1

$$p(x',z) \approx \frac{e^{jkz} e^{jkx'^2/2z}}{z} \int_{-a}^{a} C(x) e^{-jkxx'/z} dx = \frac{e^{jkz} e^{jkx'^2/2z}}{z} F.T.[C(x)]$$

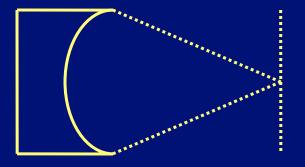
Aperture  $\leftarrow$  (F.T.)  $\rightarrow$  Radiation Pattern

When not in the far field  $\rightarrow$  effective aperture function

 $\overline{C(x)} = \left| C(x) \right| e^{-jkx^2/2z}$ 

# Focusing: An Acoustic Lens

$$C(x) = |C(x)|e^{-jkx^2/2z}$$

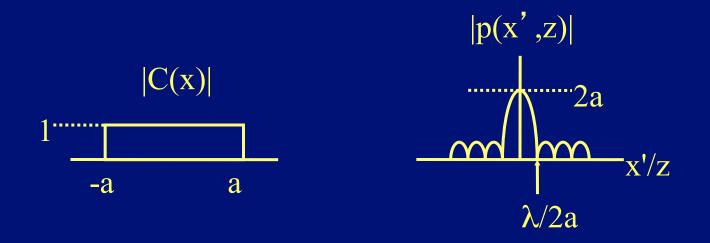


Ζ

When out of the fixed focal point:

$$C'(x) = |C(x)|e^{\frac{jkx^2}{2}(\frac{1}{z} - \frac{1}{z_0})}$$

Radiation Pattern of a Rectangular Aperture

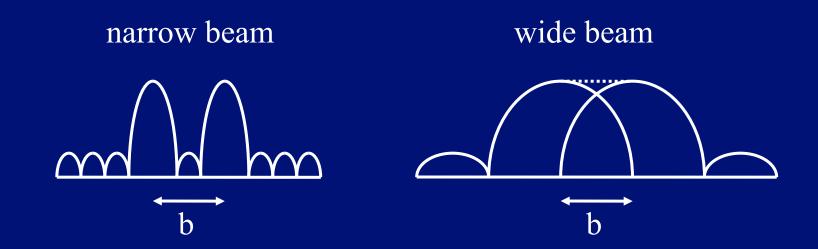


#### Beam width vs. Aperture size and frequency

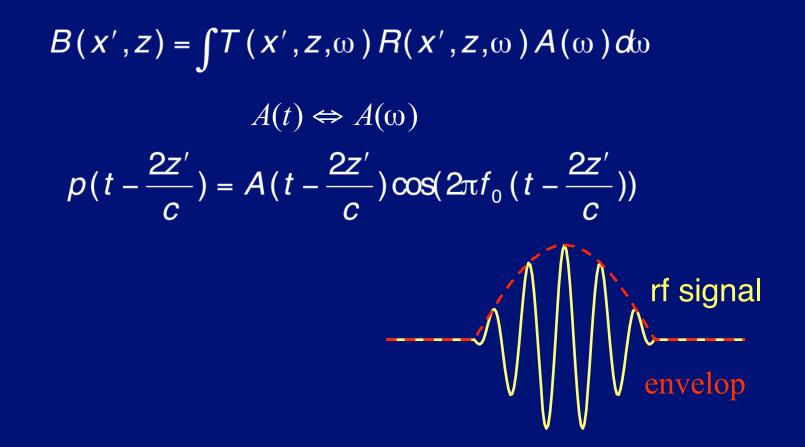
$$\left| p(x',z) \right| = \left| \int_{-a}^{a} e^{-jkxx'/z} dx \right| = \left| \frac{1}{jkx'/z} \left[ e^{jkx'a/z} - e^{-jkx'a/z} \right] \right| = \left| 2a \frac{\sin kx'a/z}{kx'a/z} \right| = \left| 2a \sin c(\frac{kx'a}{z}) \right|$$

# Lateral Resolution

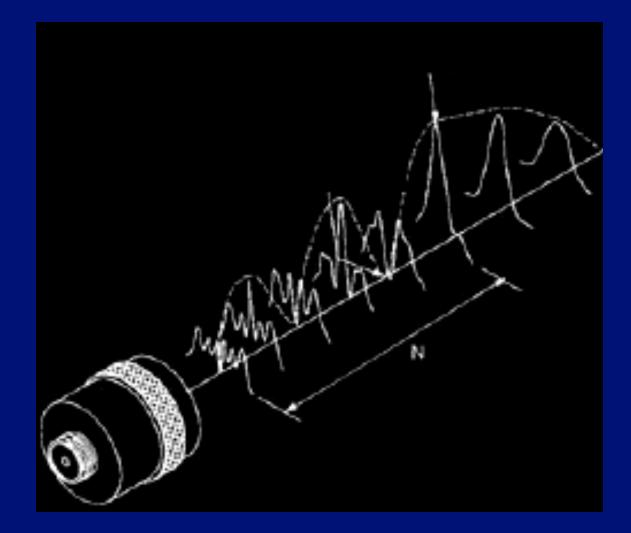
- Frequency ↑
- Aperture size ↑
- -3 dB, -6 dB, -10 dB, -20 dB,...etc.



### CW to Wideband

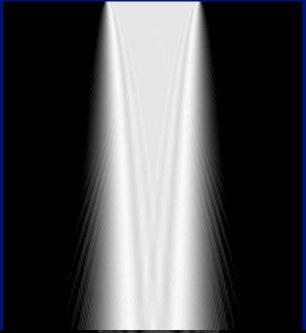


# **Radiation Pattern**



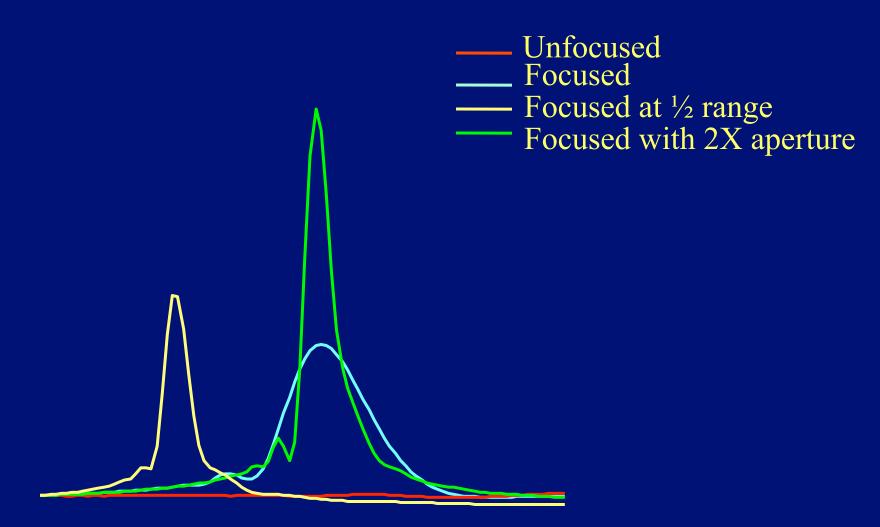
#### Unfocused

#### Focused

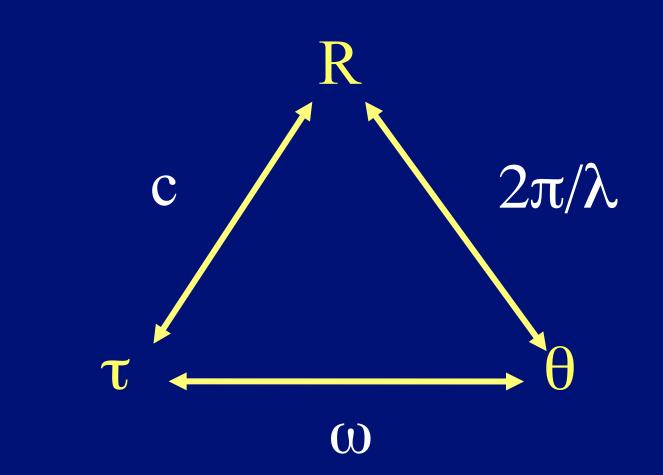


Focused at <sup>1</sup>/<sub>2</sub> range Focused with twice the aperture

### Axial Intensity



### **Diffraction and Propagation Delays**



### CW to Pulse Wave

$$p(x',z,t) = \int_{-a}^{a} A(t-\tau(x,x',z)) \cos \omega_0 (t-\tau(x,x',z)) dx$$
  

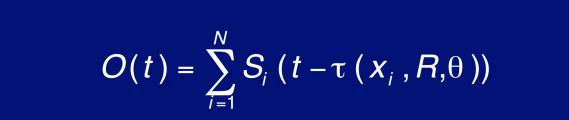
$$\tau(x,x',z) = \left( (x-x')^2 + z^2 \right)^{\frac{1}{2}} / c$$
  
In Fresnel region  $\tau(x,x',z) \approx \frac{z}{c} + \frac{(x-x')^2}{2zc}$   
Apply focusing delays  $\tau'(x,x',z) = \frac{x^2}{2zc}$ 

 $p(x', z, t) = \int_{-a}^{a} A(t - \tau(x, x', z) + \tau'(x, x', z)) \cos\omega_{0}(t - \tau(x, x', z) + \tau'(x, x', z)) dx$  $= \int_{-a}^{a} A(t - \frac{z}{c} + \frac{xx'}{zc} - \frac{x'^{2}}{2zc}) \cos\omega_{0}(t - \frac{z}{c} + \frac{xx'}{zc} - \frac{x'^{2}}{2zc}) dx$ 

# CW to Pulse Wave

$$\begin{aligned} x' &= 0 \\ p(0, z, t) &= \int_{-a}^{a} A(t - \frac{z}{c}) \cos \omega_{0} \left( t - \frac{z}{c} \right) dx = 2aA\left( t - \frac{z}{c} \right) \cos \omega_{0} \left( t - \frac{z}{c} \right) \\ x' &\neq 0 \\ p(x', z, t) &= \operatorname{Re} \left\{ \int_{-a}^{a} A\left( t - \frac{z}{c} + \frac{xx'}{zc} - \frac{x'^{2}}{2zc} \right) e^{j\omega_{0} \left( t - \frac{z}{c} + \frac{xx'}{zc} - \frac{x'^{2}}{2zc} \right)} dx \right\} \\ &= \operatorname{Re} \left\{ e^{j\omega_{0} \left( t - \frac{z}{c} - \frac{x'^{2}}{2zc} \right)} \int_{-a}^{a} A\left( t - \frac{z}{c} + \frac{xx'}{zc} - \frac{x'^{2}}{2zc} \right) e^{j\omega_{0} \frac{xx'}{zc}} dx \right\} \\ \frac{xx'}{zc} - \frac{x'^{2}}{2zc} &\approx 0 \\ p(x', z, t) &= \operatorname{Re} \left\{ e^{j\omega_{0} \left( t - \frac{z}{c} - \frac{x'^{2}}{2zc} \right)} A\left( t - \frac{z}{c} \right) \int_{-a}^{a} e^{j\omega_{0} \frac{xx'}{zc}} dx \right\} \end{aligned}$$

# **Beam Formation Using Arrays**





# **Propagating Delays**

$$\tau(x_i, R, \theta) = \frac{\left(\left(x_i - R\sin\theta\right)^2 + R^2\cos^2\theta\right)^{1/2}}{c} = \frac{R}{c} \left(1 + \frac{x_i^2}{R^2} - \frac{2x_i}{R}\sin\theta\frac{1}{2}\right)^{1/2}}{\ln \text{ Fresnel region}}$$

$$\tau \left( x_{i}, R, \theta \right) \approx \frac{R}{c} \left( 1 + \frac{x_{i}^{2}}{2R^{2}} - \frac{x_{i}}{R} \sin \theta - \frac{x_{i}^{2}}{2R^{2}} \sin^{2} \theta \right)$$
$$= \frac{R}{c} \left( 1 - \frac{x_{i}}{R} \sin \theta + \frac{x_{i}^{2}}{2R^{2}} \cos^{2} \theta \right) = \frac{R}{c} - \frac{x_{i} \sin \theta}{c} + \frac{x_{i}^{2} \cos^{2} \theta}{2Rc}$$

Effective aperture size:  $2a \longrightarrow 2a\cos\theta$ 

# **Propagating Delays**

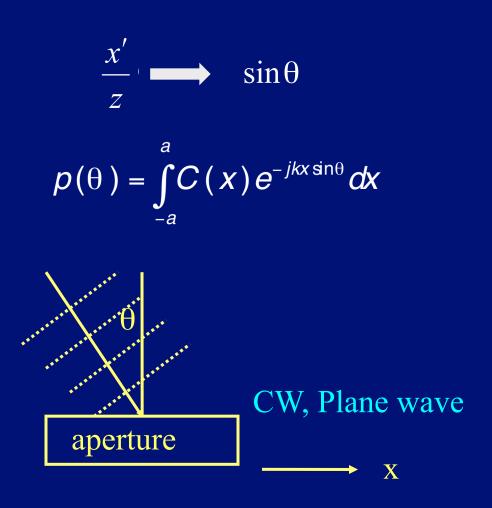
Transmit:

$$\tau^{T}(x_{i}, R, \theta) = -\frac{x_{i} \sin \theta}{c} + \frac{x_{i}^{2} \cos^{2} \theta}{2Rc}$$

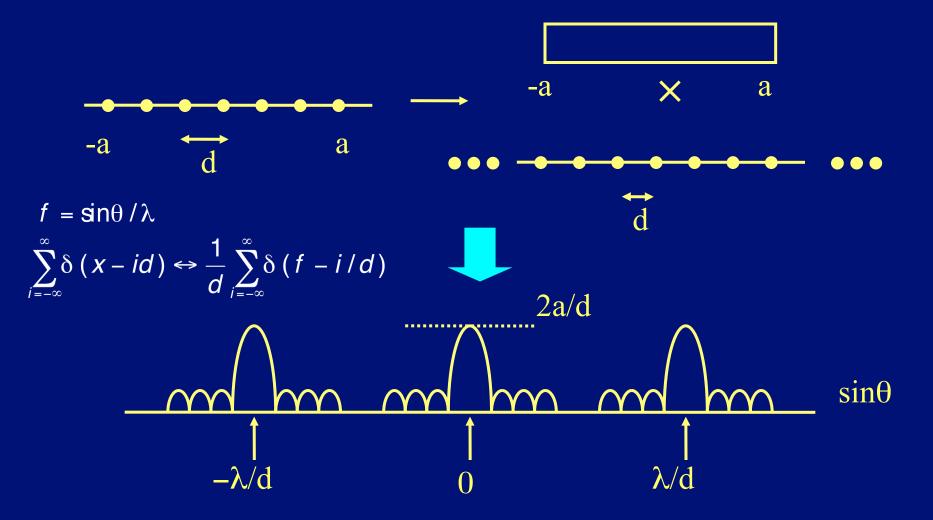
Receive:

 $\tau^{R}(x_{i}, R, \theta) = \frac{2R}{c} - \frac{x_{i}\sin\theta}{c} + \frac{x_{i}^{2}\cos^{2}\theta}{2Rc}$ 

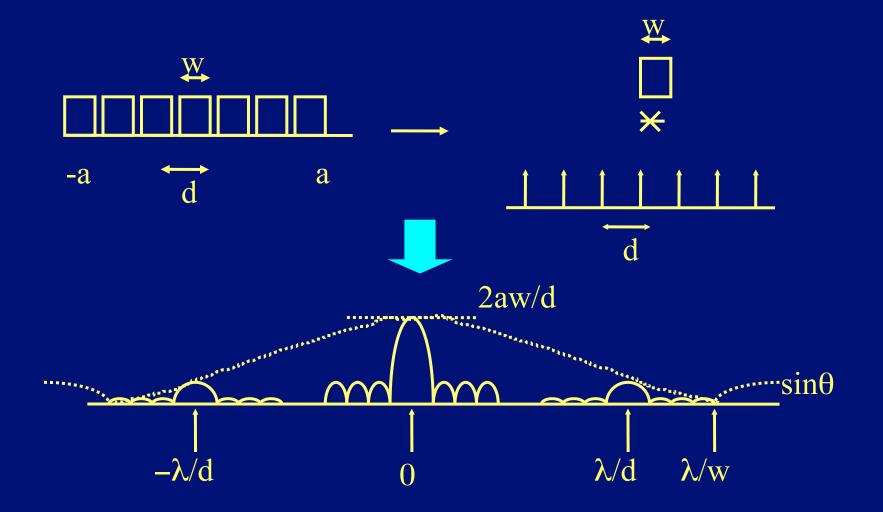
# Beam Forming Using Arrays



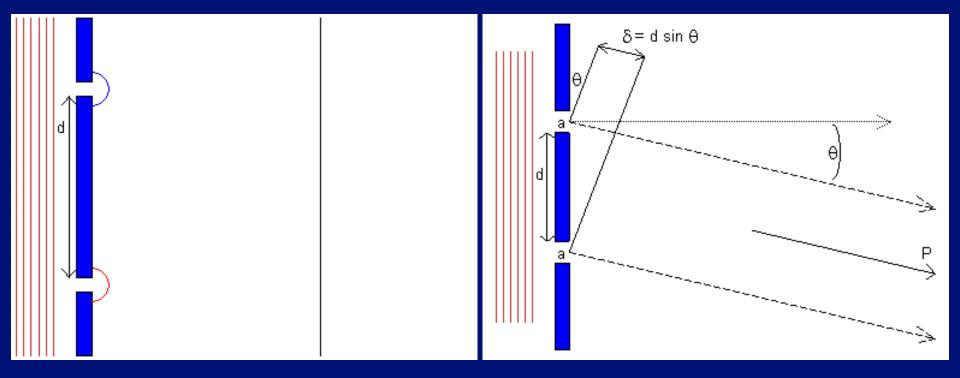
# Radiation Pattern of a Sampled Aperture (I)



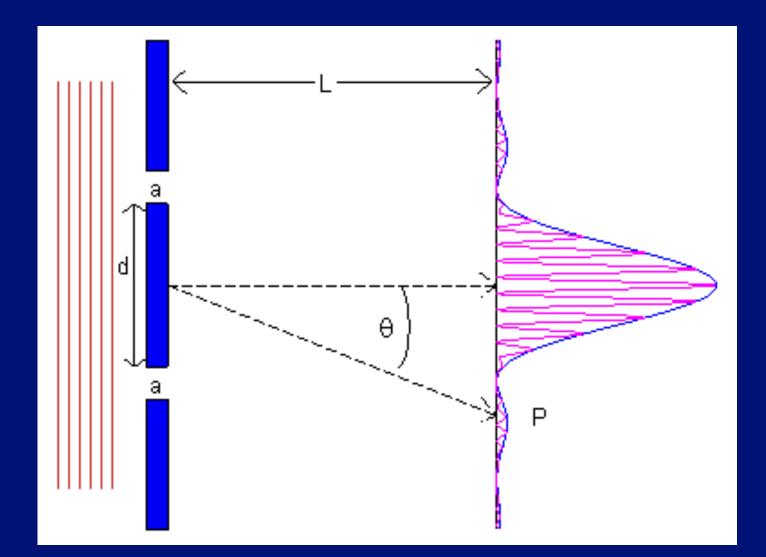
# Radiation Pattern of a Sampled Aperture (II)



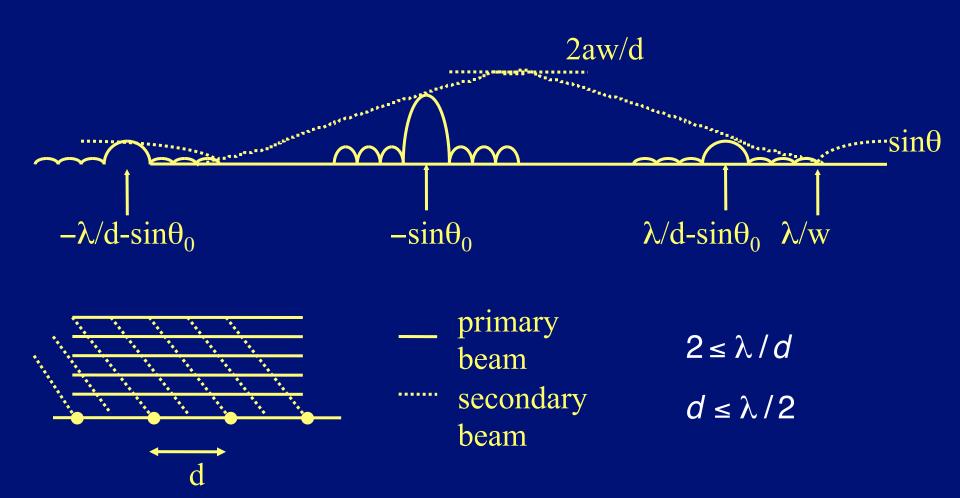
# Interference



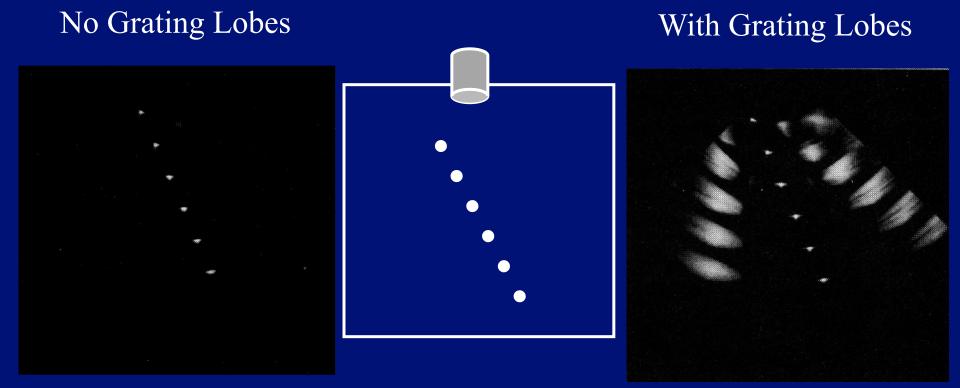
### Interference



# Array Steering and Grating Lobes



# Grating Lobes

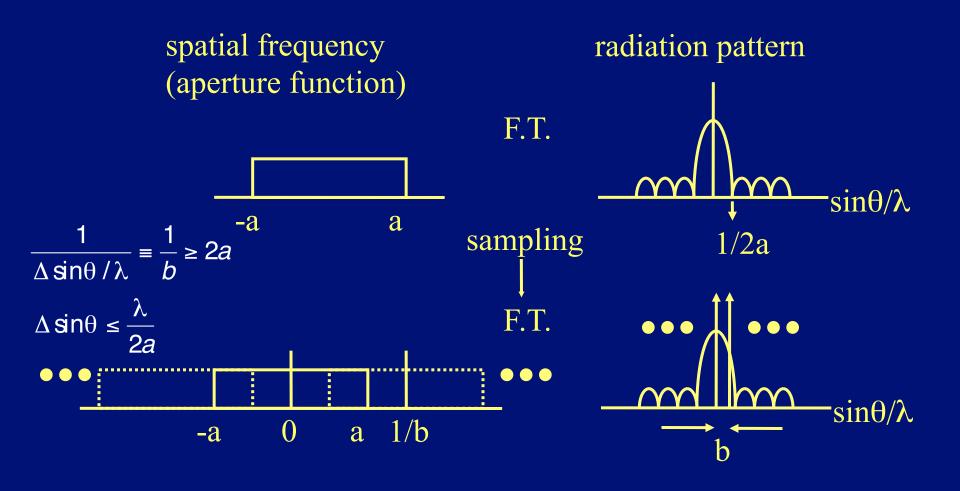


# Grating Lobes (II)

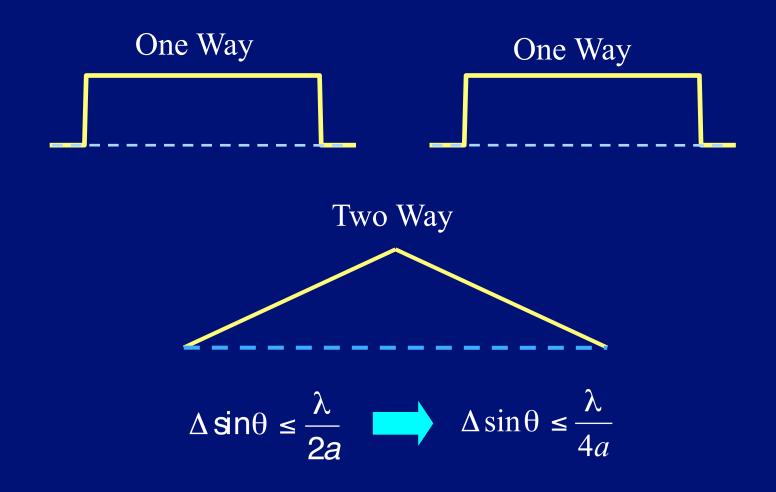
 $2\pi f_0\left(\tau\left(\overline{x_i}, \overline{R}, \theta\right) - \tau\left(x_{i+1}, \overline{R}, \theta\right)\right) > \pi$ 

$$2\pi f_0(\frac{R}{c} - \frac{x_i \sin\theta}{c} - \frac{R}{c} + \frac{x_{i+1} \sin\theta}{c}) = \frac{2\pi f_0 \sin\theta}{c} (x_{i+1} - x_i) = \frac{2\pi \sin\theta d}{\lambda} > \pi$$
$$\sin\theta > \frac{\lambda}{2d} \qquad \Longrightarrow \qquad d \le \lambda/2$$

#### **Beam Sampling**



#### **Beam Sampling**



## Beam Sampling (II)

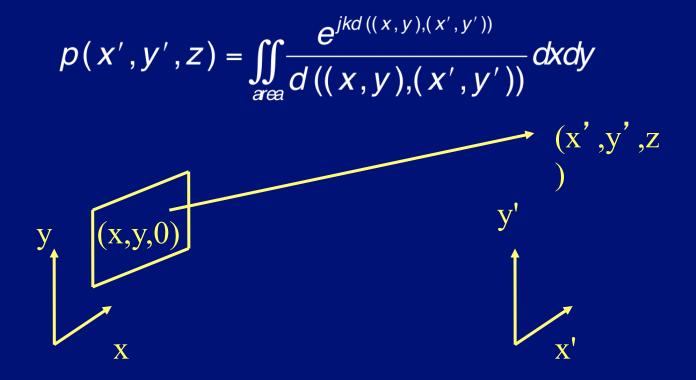
One Way:

 $2\pi f_0 \left( \tau \left( a, R, \theta_{i+1} \right) - \tau \left( -a, R, \theta_{i+1} \right) - \left( \tau \left( a, R, \theta_i \right) - \tau \left( -a, R, \theta_i \right) \right) \right)$  $= \frac{2\pi f_0}{c} \left( 2a\Delta \sin \theta \right) = \frac{2\pi f_0}{c} \frac{2a\lambda}{2a} = 2\pi$ 

$$\Delta \sin \theta \leq \frac{\lambda}{2a}$$

# 2D Apertures

#### **Diffraction for 2D Apertures**



#### **Diffraction for 2D Apertures**

Separable aperture function:

C(x,y) = C(x)C(y) $B(x',y',z) = B(x',z) \times B(y',z) = F.T.[C(x)] \times F.T.[C(y)]$ 

Circular aperture  $\rightarrow$  Jinc radiation pattern.

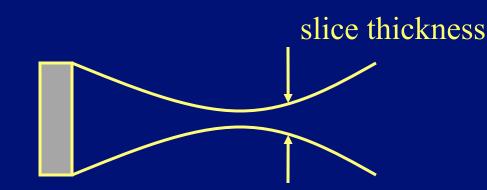
# Two-Dimensional Transducer Arrays

# Motivations: Elevational Focusing

- 1D arrays have only fixed elevational focusing capabilities. The elevational focusing quality is determined by a mechanical lens.
- 2D arrays must be used in order to have electronic, dynamic 3D focusing.

## Motivations: Elevational Focusing

• Although not apparent, elevational focusing quality determines the "slice thickness" and is critical in image quality (including contrast resolution, noise characteristics and elevational resolution).



# Motivations: Real-Time 3D Imaging

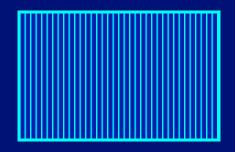
- Current 3D imaging (including flow imaging) is done by reconstruction using a set of 2D images. This is not real-time.
- Fully sampled (i.e., spatial Nyquist criterion is satisfied in both directions) arrays must be used to allow full 3D focusing and steering capabilities.

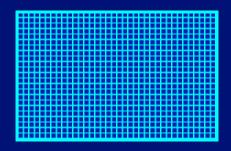
# Complications

- For a fully sampled aperture with a typical size, the total channel count may exceed 10,000.
- As the element size decreases, electrical impedance significantly increases, thus resulting in poor signal to noise ratio.

# Complications

• Inter-connection from each channel to the front-end electronics becomes complicated with 2D arrays.





#### Reduction of Channel Count

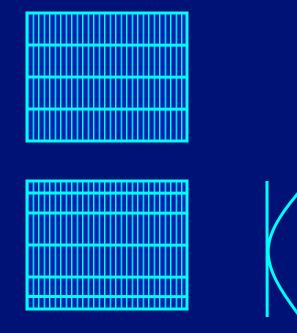
- Sparse array:
  - A random selection of elements are removed from the periodic dense array. Only a fraction of the original elements remains.
  - Mainlobe is un-affected. Grating lobes are avoided. Sidelobes are higher.
  - Electrical impedance is un-changed.
  - Difficult to manufacture.

#### Reduction of Channel Count

- 1.5D array:
  - Aperture in elevation is under-sampled.
  - Electrical impedance is reduced.
  - Total channel count is reduced.
  - Lack of elevational steering.
  - Full 3D focusing quality on the 2D image plane.
  - Also known as an-isotropic arrays.

# Sampling of 1.5D Arrays

- Uniform sampling.
- Fresnel sampling.



• Geometric delays are symmetric.

### Sparse Periodic Arrays

• Despite of the periodicity, grating lobes are avoided by placing them at different locations.



## Sparse Periodic Arrays

- Two-way beam pattern is determined by two-way aperture function, i.e., the convolution of the transmit aperture with the receive aperture.
- By carefully choosing the aperture functions, desired response can be synthesized.

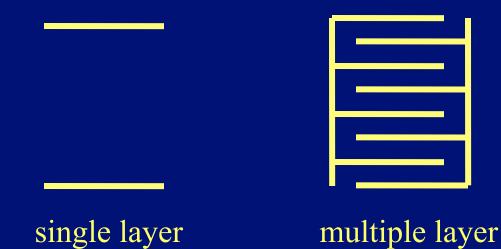
#### Sparse Periodic Arrays

- Only valid for CW and in-focus. 4-to-1 reduction is reasonable.
- Signal-to-noise ratio is affected.
- In general, this is a synthetic aperture approach.
- This approach can be extended to 2D.

# Lowering Impedance

- Electrical impedance significantly increases (high resistance and low capacitance) with small transducer area.
- For typical system characteristics, large impedance means poor sensitivity.
- Impedance can be reduced by many methods, including using multiple layer piezoelectric material.

• Acoustically in series and electrically in parallel.



- On transmit, the acoustic output pressure is increased by a factor of N (number of layers) assuming the same drive voltage.
- The output pressure is also increased by matching the impedance.

- On receive, the received voltage is reduced by a factor of N assuming the same returning pressure.
- Capacitance is increased by a factor of N<sup>2</sup>, due to the parallel connection and smaller distance between plates.
- The receive improvement depends on specific situations.

- Both KLM and finite element models have been used to predict the performance and compared to measurement results.
- An alternative method is to have multiple layers on transmit and signal layer on receive.
- The coaxial cable capacitance can be reduced by integrating front-end with transducers.

# Complications for Real-Time 3D Imaging

- Channel count.
- System complexity associated with increased channel count.
- The number of beams in a 3D imaging is dramatically increased, thus reducing "frame rate".
- Parallel beam formation is desired.

- Computer Homework #2: Beam Formation
- Due 12:00pm 4/24/2012 by emailing to paichi@ntu.edu.tw;

r99945010@ntu.edu.tw

Load hw2 dat.mat. In this data file, apertureU defines a uniform aperture and apertureH defines an aperture with non-uniform weighting. The spacing between two points in both cases is defined by d0 in mm. The vector pulseF defines a pulse spectrum of a particular excitation with the frequency axis specified by faxis (in MHz). Finally, the sound propagation velocity is defined by soundV in mm/usec. In all figures, please label all axes.

- 1. Assuming a continuous wave at 5MHz from the far field and zero incidence angle, plot the magnitude of the one-way diffraction patterns for both apertureU and apertureH (in dB). The horizontal axis should be  $\sin\theta$  from -1 to 1. (20%)
- 2. Assuming a pulse wave which has the frequency response specified by pulseF and faxis, plot the magnitude of the one-way, far-field diffraction patterns (zero incidence angle) for both apertureU and apertureH (in dB). The horizontal axis should be  $\sin\theta$  from -1 to 1. (20%)

- 3. Calculate the –6dB and –20dB mainlobe widths of the diffraction patterns obtained from 1 and 2. Comment on your answers and the sidelobe levels between two different apodization schemes. (20%)
- 4. Repeat 3 if the incidence angle is at 45 degrees. Justify your answers (20%)
- 5. Repeat 2 and 3 if the aperture is focused at 60 mm but the diffraction patterns are drawn at 55 mm and 65 mm, respectively. Comments on your answers. (20%)
- 6. (Bonus) Use the simulation programs to investigate dual beam formation (transmit/receive aperture, beam spacing).